

# **蓝牙链接** BLUETOOH LINK







 微信扫一扫二维码 (Scan the QR code with WeChat)



 点击右上角按钮,选择浏览器下载(如图所示) (Click the button on the top right corner and select the browser to download (as shown in the picture))





3、点击下载安装(如图所示) (Click to download and install (as shown in the figure))



#### <APP与飞机蓝牙连接 > APP and aircraft Bluetooth connection

 如图一所示: 先将蓝牙插入飞控上方UART并将蓝牙模块 固定在飞控则面

As shown in Figure 1: First, insert the Bluetooth into the UART above the flight control and connect the Bluetooth module, then fix on the side of the flight control.



#### 打开遥控器与飞机连接成功 Turn on the remote control and connect to the aircraft successfully.

3、打开手机APP (如图所示) 点击始终允许 Open the mobile APP (as shown in the figure) and click Always Allow



### <APP与飞机蓝牙连接 > APP and aircraft Bluetooth connection

 如下图所示:点击右下角的蓝牙按钮→允许→始终允许 As shown below: Click the Bluetooth button on the bottom right corner > Allow > Always Allow



 如下图所示:点击右上角的喇新按钮一在下方列表里翻 转找到goosky-Android进行连接。点击面对 As shown below: Click the refresh button on the top right comer > flip through the list below to find GOOSKY-Android to connet > choose Pair





#### 6、连接成功后(APP如下图界面)飞控指示灯→蓝灯快闪 (注:以飞控蓝灯闪烁为准)

After the connection is successful (APP interface as shown below) the blue light on the flight control indicator flashes quickly (Note: Subject to the flashing blue light of the flight control)



## < 板块功能介绍 >

Introduction to the function of the section

 1、点击左上角关于按钮查看版本号→升级程序→恢复出厂设置 →网址

Click the About button in the upper left corner can check the version number and upgrade program, restore default and also can view the URL.

E About
GOOSKY
Version No.1.0.29
WWX.000-IP/COM

 2、点击开始调参界面介绍:电压→speed滚转速率→agile灵敏度 →gyro感度

Interface introduction after clicking the PARAMETER TURNING: From top to bottom are voltage, speed roll rate, agile sensitivity, gyro sensitivity



< 板块功能介绍 >

Introduction to the function of the section

3、点击机械设置: servo舵机中位 '开/关' →主旋翼螺距→保存

Click the mechanical setting: From top to bottom are servo center position 'on/off' , main blade pith, save

